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Erratum: Symanzik improvement with dynamical charm: a 3+1 scheme for Wilson quarks



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We correct for typos and add a few missing details that can help to reproduce our calculations. The results of our original paper remain unchanged.

1. We add information to the 2^{nd} sentence following eq. (4.3):

The normalization factor \mathcal{N} , which implies $\Phi_1 = g_0^2 + \mathrm{O}(g_0^4)$ in perturbation theory, has been derived in [41] for the plaquette gauge action. For our setup with tree level improved Lüscher-Weisz gauge action we have to recompute this normalisation factor which amounts to replacing the lattice time-momentum gauge propagator in eq. (2.48) of ref. [41] with that of choice B provided in appendix B of ref. [43]. Otherwise, the numerical calculation proceeds along the lines of [41], leading to the values quoted in table 4, which have entered into our results.

T/a	\mathcal{N}
8	0.014804755
12	0.016141622
16	0.016638624
20	0.016688084
24	0.017004531

Table 4. Normalisation factors for the renormalised coupling Φ_1 in the SF with tree level improved Lüscher-Weisz gauge action, T = L and vanishing background field.

- 2. We add a sentence before eq. (5.3):
 - ... correlations and finally to $m'^{ij}(x_0)$. For the precise definition, the reader is advised to consult [25].
- 3. A minus sign was missing in eq. (5.4). The correct formula reads

$$c_{\mathcal{A}} = -\frac{r'^{ij}(y_0) - r^{ij}(y_0)}{s'^{ij}(y_0) - s^{ij}(y_0)} \quad \text{at } y_0 = \frac{3}{4}T$$
 (5.4)

4. We replace the caption of table 2 as follows:

Table 2. Results of the individual improvement condition runs along the LCP for various input values of c_{sw} . Beside g_0 , κ_l and κ_c , we quote the corresponding current quark masses $m^{ud}(x_0)$ at $x_0 = T^*/2$ with one-loop c_A , the improvement condition mass $M^{ud}(x_0, y_0)$ for $x_0 = \frac{1}{2}T^*$ and $y_0 = \frac{3}{4}T^*$, and the mass difference ΔM^{ud} from eq. (5.6). Errors from the relation $g_0^2 \leftrightarrow T^*/a$ are neglected.

Note the change from $x_0 = \frac{1}{4}T^*$ to $x_0 = \frac{1}{2}T^*$.

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